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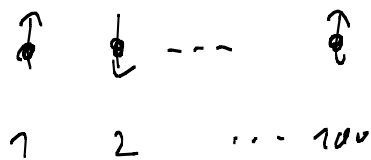
The stabilizer

formalism.

(Or: Why it sucks)

I) Why state vectors are bad

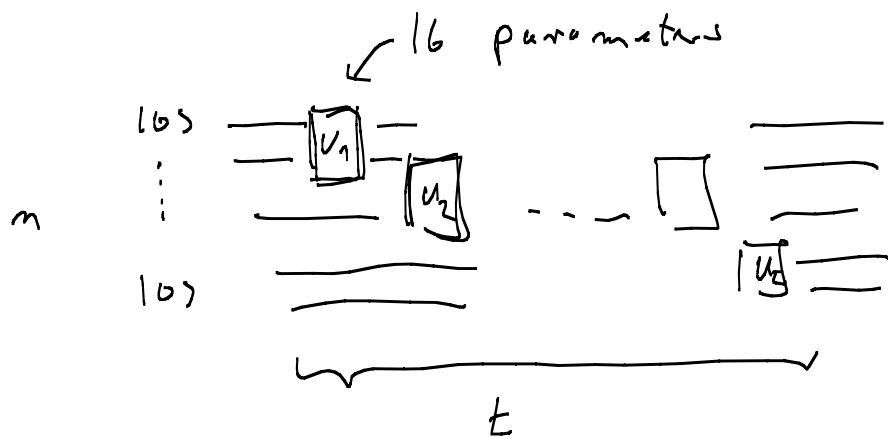
Pessimist QM doesn't work



$$\dim \mathcal{H} = 2^{100}$$

1975 There's not enough paper in the universe.

Optimist



$$\int |\mathcal{I}(U_1, \dots, U_G)\rangle$$

QM has a chance.

Physical

states have

few params.

$$16 \cdot \frac{n(n-1)}{2} \cdot t \ll 2^n$$

P: OK, but talk on

observable

$$\bullet A_1 \otimes A_2 \dots \otimes A_n$$

$$\bullet |\mathcal{I}(U_1, \dots, U_G)\rangle$$

How to get

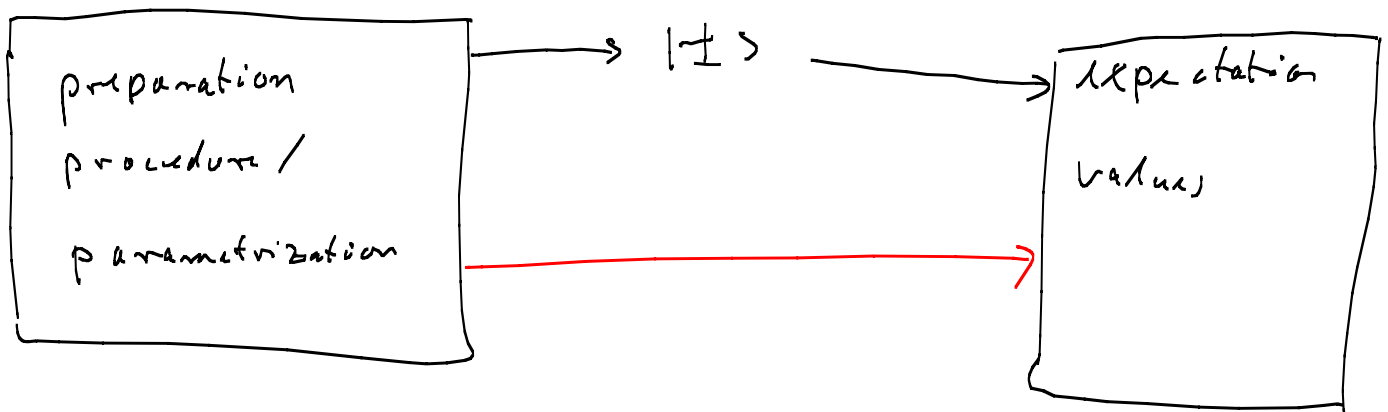


$$f(u_1, \dots, u_t) = \sum_{\substack{|A_1| a \dots a |A_n| \\ |A|}} \langle \Psi | (U_{t_1} \dots U_{t_n}) | A_1 a \dots a A_n | \Psi \rangle$$

Not enough time in the universe.

Gi I will identify a subset of states in $(\mathbb{C}^2)^{\otimes n}$ such that

- have few param.
- possible to efficiently compute some expectation values
- interesting.



II Stabilizers

a) Pauli matrices

$$\underline{1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \sigma_0 \quad \checkmark$$

$$- X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \sigma_1$$

$$- Y = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} = \sigma_2$$

$$Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \sigma_3$$

b) composition

$$X \cdot Y = i Z$$

$$Z \cdot X = i Y$$

$$Y \cdot Z = i X$$

c) square to 1

$$X^2 = \underline{1}$$

$$Y^2 = \underline{1}$$

$$Z^2 = \underline{1}$$

d) anti commute

$$X Y = - Y X$$

$$\sigma_i \sigma_j = - \sigma_j \sigma_i$$

$$i \neq j \quad i, j = 1, 2, 3$$

e)

$$\begin{aligned} \text{tr } X \\ &= \text{tr } Y \\ &= \text{tr } Z = 0 \end{aligned}$$

$$\text{tr } \underline{1} = 2.$$

A) n -qubit Pauli operators

$$P^{(n)} = \{ \sigma_{i_1} \otimes \sigma_{i_2} \otimes \dots \otimes \sigma_{i_n} \mid i_1, \dots, i_n = 0, 1, 2, 3 \}$$

$\sigma = +1, -1, +i, -i$

Ex.: $P^{(2)} \ni \mathbb{1} \otimes X, Z \otimes Z, -i Y \otimes X \dots$

O's idea: Look for interesting states among the eigenvectors of Pauli matrices.

Generalize

Let $g_1, \dots, g_k \in P^{(n)}$

such that

• they all commute: $g_i g_j = g_j g_i$

• $g^2 = \mathbb{1} \quad \forall g \in S$

• S stabilizer group

$\langle g_1, \dots, g_k \rangle$

Def.: The stabilizer space V_S is the set of vectors $|\psi\rangle$

such that

$$g(\pm) = (\pm)$$

for all $g \in S$.

Q1 . When is V_S interesting?

. Given S , how do I get it?

\rightarrow analyze these gr.

$$I) S = \langle g_1, \dots, g_k \rangle$$

$$g_1 g_2 g_4 g_2$$

$$= g_1 \underbrace{g_2 g_2}_{1} g_4 = g_1 g_4$$

$$= g_1^{x_1} \cdot g_2^{x_2} \cdot g_3^{x_3} \cdot g_4^{x_4} \cdot \dots \cdot g_k^{x_k}$$

$$S \ni g \sim \begin{matrix} \uparrow & & & & \uparrow & & & & \uparrow \\ g_1^{x_1} & \cdot & g_2^{x_2} & \cdot & \dots & \cdot & g_k^{x_k} \\ 2 & \cdot & 2 & \cdot & \dots & \cdot & 2 & = 2^k \end{matrix} \quad x_i = 0/1$$

$$|S| = 2^k$$

Problem: $S \rightarrow$ stabilizer space?

\uparrow solved by looking at

$$P_S = \frac{1}{2^k} \sum_{g \in S} g.$$

$$1) \quad \text{tr } P_S = \frac{1}{2^k} \sum_{g \in S} \text{tr } g$$

$$\begin{aligned} & \frac{\text{tr } \sigma_{i_1} \otimes \dots \otimes \sigma_{i_m}}{\text{tr } \sigma_{i_1}} \dots \text{tr } \sigma_{i_m} \\ &= \begin{cases} 0 & \text{if } g \neq \mathbb{1} \otimes \dots \otimes \mathbb{1} \\ 2^m & \text{if } g = \mathbb{1} \otimes \dots \otimes \mathbb{1} \end{cases} \end{aligned}$$

$$= \frac{2^m}{2^k} = \underline{2^{m-k}}.$$

$$2) \quad \underline{P_S \cdot P_S} = \frac{1}{2^k} \cdot \frac{1}{2^k} \sum_{g \in S} g \sum_{h \in S} h$$

$$\begin{aligned} &= \frac{1}{2^k} \cdot \frac{1}{2^k} \sum_g \left(\sum_h g h \right) \\ &= \sum_h h \end{aligned}$$

$$= \frac{1}{2^k} \sum_{g \in S} P_S = \underline{P_S}.$$

$\leadsto P_S$ is a projection operator

\leadsto it projects on $\text{tr } P_S = 2^{n-k}$
dimensional space.

Exam: take n Pauli operators

$$g_1, \dots, g_n$$

$$\leadsto S = \langle g_1, \dots, g_n \rangle$$

$$\leadsto P = \frac{1}{2^n} \sum_{g \in S} g$$

$$\leadsto P = \underbrace{|\psi\rangle\langle\psi|}_{\text{stabilizer state}}$$

Observables

I have $|\psi\rangle$, a stabilizer state.

Have observable, e.g. $h = Z \otimes \dots \otimes Z$

$$\text{tr} [|\psi\rangle\langle\psi| \quad Z \otimes \dots \otimes Z]$$

$$= \text{tr} [P_S \quad \underbrace{Z \otimes \dots \otimes Z}]$$

$$= \frac{1}{2^m} \sum_{g \in S} \text{tr} [g \cdot h]$$

$$= \begin{cases} 2^m & g \cdot h = \underline{1} \dots \underline{1} \\ 0 & \text{else} \end{cases}$$

$$= \begin{cases} 2^m & g = h \\ 0 & \text{else} \end{cases}$$

$$= \begin{cases} 1 & h \in S \\ 0 & \text{else} \end{cases}$$

Fantastic!

